Matrix elasticity regulates the optimal cardiac myocyte shape for contractility

Megan L. McCain,* Hongyan Yuan,* Francesco S. Pasqualini, Patrick H. Campbell, and Kevin Kit Parker

Disease Biophysics Group, Wyss Institute for Biologically Inspired Engineering, School of Engineering and Applied Sciences, Harvard University, Cambridge, Massachusetts

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McCain ML, Yuan H, Pasqualini FS, Campbell PH, Parker KK. Matrix elasticity regulates the optimal cardiac myocyte shape for contractility. *Am J Physiol Heart Circ Physiol* 306: H1525–H1539, 2014. First published March 28, 2014; doi:10.1152/ajpheart.00799.2013.—Concentric hypertrophy is characterized by ventricular wall thickening, fibrosis, and decreased myocyte length-to-width aspect ratio. Ventricular thickening is considered compensatory because it reduces wall stress, but the functional consequences of cell shape remodeling in this pathological setting are unknown. We hypothesized that decreases in myocyte aspect ratio allow myocytes to maximize contractility when the extracellular matrix becomes stiffer due to conditions such as fibrosis. To test this, we engineered neonatal rat ventricular myocytes into rectangles mimicking the 2-D profiles of healthy and hypertrophied myocytes on hydrogels with moderate (13 kPa) and high (90 kPa) elastic moduli. Actin alignment was unaffected by matrix elasticity, but sarcomere content was typically higher on stiff gels. Microtubule polymerization was higher on stiff gels, implying increased intracellular elastic modulus. On moderate gels, myocytes with moderate aspect ratios (~7:1) generated the most peak systolic force compared with other cell shapes. However, on stiffer gels, low aspect ratios (~2:1) generated the most peak systolic work. To compare the relative contributions of intracellular vs. extracellular elasticity to contractility, we developed an analytical model and used our experimental data to fit unknown parameters. Our model predicted that matrix elasticity dominates over intracellular elasticity, suggesting that the extracellular matrix may potentially be a more effective therapeutic target than microtubules. Our data and model suggest that myocytes with lower aspect ratios have a functional advantage when the elasticity of the extracellular matrix decreases due to conditions such as fibrosis, highlighting the role of the extracellular matrix in cardiac disease.

Address for reprint requests and other correspondence: K. K. Parker, Harvard School of Engineering and Applied Sciences, 29 Oxford St., Pierce Hall 321, Cambridge, MA 02138 (e-mail: kkparker@seas.harvard.edu).

CARDIOVASCULAR DISEASES, such as heart failure, are the leading cause of death in the United States (43). Heart failure is usually initiated by a pathological stimulus, such as hypertension or aortic valve stenosis, that increases hemodynamic afterload on the left ventricle (14). In response to elevated load, the ventricular wall thickens to normalize wall stress, known as concentric hypertrophy (27, 37). This gross morphological change in organ structure is potentiated by changes in cell shape; traction force microscopy; contraction; biophysics

* M. L. McCain and H. Yuan contributed equally to this work.

in healthy and hypertrophied hearts, respectively (2, 23). To explain our experimental results and delineate the contributions of intracellular and extracellular elasticity, we developed a mathematical model, which predicted that extracellular elasticity has a greater pathological impact on contractility than intracellular elasticity, thereby identifying the extracellular matrix as a potentially more effective therapeutic target than microtubules. Together, our results suggest that myocyte contractility depends on both myocyte shape and the elasticity of the extracellular matrix.

**Glossary**

- **a**: Surface area of the cell
- **s**: Length-to-width cell aspect ratio
- **b**: Width of the cell
- **c**: A nondimensional parameter that accounts for unknown geometric factors between the cell and the 2-D gel
- **γ**: Maximum percent cell shortening rate
- **Em**: Young's modulus of the matrix
- **Ec**: Young's modulus of the cell
- **ε**: Percent cell shortening
- **ε_p**: Percent cell shortening at peak systole
- **f_x**: Force vector \( i \)
- **f_x,i**: \( x \)-magnitude of force vector \( i \)
- **f_y,i**: \( y \)-magnitude of force vector \( i \)
- **F_x**: Longitudinal contractile force
- **F_x,p**: Longitudinal contractile force at peak systole
- **H**: Height of the cell
- **l**: Left side of cell
- **L**: Diastolic length of the cell
- **OOP**: Orientational order parameter
- **σ**: Contractile stress
- **σ_i**: Traction stress vector \( i \)
- **σ_o**: Contractile isometric stress
- **σ_p**: Contractile stress at peak systole
- **r**: Right side of cell
- **t**: Time
- **t_p**: Time to peak systole
- **TFM**: Traction force microscopy
- **u_i**: Displacement vector \( i \)
- **u_x,i**: \( x \)-magnitude of displacement vector \( i \)
- **u_y,i**: \( y \)-magnitude of displacement vector \( i \)
- **ν**: Poisson ratio
- **w_p**: Peak systolic work
- **w_x,p**: Peak systolic longitudinal work

**METHODS**

**Polyacrylamide gel preparation.** Polyacrylamide gel substrates were fabricated using previously published protocols (36, 41). Glass coverslips (25 mm) were activated by treatment with 100 mM NaOH for 5 min, 0.5% (3-aminopropyl)triethoxysilane in 95% ethanol for 5 min, and 0.5% glutaraldehyde for 30 min. Polyacrylamide gel solutions with 13-kPa and 90-kPa elastic modulus were created with the following acrylamide/bis concentrations: 13 kPa, 7.5/0.3%; 90 kPa, 12/0.6%. Gel solutions were doped with 200 nm Alexa 488 fluorescent beads (Invitrogen, Carlsbad, CA) at a 1:100 dilution and streptavidin acrylamide (S-21379, Invitrogen). Tetramethylethenediamine (0.25%) and ammonium persulfate (0.08%) were added to cross-link gel solutions. Fifteen to 20 μl of gel solution was pipetted onto activated coverslips and covered with 18-mm untreated glass coverslips. After 15 min, gels were polymerized and the top coverslip was removed. Gels were rinsed and stored in PBS at 4°C. Prior to microcontact printing, the surface of the gels was dried by incubating in a 37°C oven for 10–15 min.

**Microcontact printing.** Polydimethylsiloxane (Sylgard 184, Dow Corning, Midland, MI) stamps were prepared using standard microfabrication techniques (6, 9). We designed a pattern of rectangles with conserved surface area (~1,200 μm²) and varying aspect ratios: 2:1 (25 μm × 50 μm), 4:1 (17 μm × 68 μm), 8:1 (12 μm × 96 μm), and 12:1 (10 μm × 120 μm) in AutoCAD (Autodesk, San Rafael, CA), which was etched onto a photolithographic mask. The mask was used to shield selective areas of a silicon wafer spin-coated with SU-8 2002 (Microchem, Newton, MA) from UV light exposure using a mask aligner (ABM, Woburn, MA). Exposed wafers were baked, incubated in SU-8 Developer (Microchem, Newton, MA), cleaned with isopropyl alcohol, and used as templates for stamps.

**Biotinylated fibronectin (FN) was prepared by incubating human FN (BD Biosciences, Franklin Lakes, NJ) with Sulfo-NHS-LC-Biotin (Pierce, Rockford, IL) overnight (41). Stamps were sonicated in 95% ethanol, dried, and coated with 200 μg/ml biotinylated FN. After 1 h, excess FN solution was blown off the stamp with compressed air and stamps were inverted onto dried polyacrylamide gel surfaces. Stamps were then peeled off the gels, and coverslips were stored in PBS at 4°C until cell seeding.

**Neonatal rat ventricular myocyte culture.** Two-day-old Sprague-Dawley rats were euthanized according to protocols approved by the Harvard University Animal Care and Use Committee (6). Ventricular tissue was isolated, minced, and placed in trypsin solution (1 mg/ml, Invitrogen) overnight at 4°C. After 11–13 h, tissues were incubated in collagenase solution (1 mg/ml, Worthington Biochemical, Lakewood, NJ) at 37°C and pipetted several times to dissociate tissues and form a cell suspension. Cell suspensions were strained to remove undigested tissue and preplated twice to reduce nonmyocyte cell populations. Purified cell suspensions were seeded onto gel coverslips at a concentration of 10,000–50,000 cells/cm² and cultured in supplemented M199 (10 mM HEPES, 0.1 mM MEM nonessential amino acids, 20 mM glucose, 2 mM L-glutamine, 1.5 μM vitamin B-12, and 50 U/ml penicillin) with 1% fetal bovine serum for 3 days. Myocytes were treated with 0.2 μM epinephrine after 3 days in culture to stimulate spontaneous beating.

**Immunostaining.** To stain for actin and α-actinin, myocyte coverslips were fixed with 4% paraformaldehyde and 0.05% Triton X for 5 min. To stain for microtubules, coverslips were rinsed with 37°C microtubule stabilizing buffer (65 mM PIPES, 25 mM HEPES, 10 mM EGTA, 3 mM MgCl₂, pH 6.9), permeabilized with 1% Triton X in microtubule stabilizing buffer for 1 min, and fixed in 3% paraformaldehyde in microtubule stabilizing buffer for 10 min (45).

Mouse anti-α-actinin (Sigma-Aldrich, St. Louis, MO) or mouse anti-α-tubulin (Sigma-Aldrich, St. Louis, MO) antibodies were added at 1:200 for 1–2 h at room temperature. The following secondary antibodies and dyes were added at 1:200 for 1–2 h at room temperature: DAPI (Invitrogen), Alexa Fluor 488 phalloidin (Invitrogen), and Alexa Fluor 546 goat anti-mouse IgG (H + L) (Invitrogen). Stained coverslips were then mounted on a glass slide using ProLong Gold Anti-Fade Reagent (Invitrogen).

**Imaging and image processing.** Stained myocytes were imaged using a Zeiss LSM 5 LIVE confocal microscope (Zeiss, Oberkochen, Germany). Z-stacks of individual myocytes were collected using a 100× Plan-Apochromat oil objective. For actin z-stacks, software based on fingerprint detection algorithms was used to identify orientation vectors of positive pixels in maximum projection images (18). The orientational order parameter of the vectors was then calculated, which ranges from 0 for completely isotropic systems to 1 for completely anisotropic systems (25). To determine sarcomere length and sarcomere content, sarcomeric α-actinin immunostains were first preprocessed in ImageJ (NIH, Bethesda, MD) to highlight the fila-

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mentous structure of the cell cytoskeleton through a tubeness operator (46) and then analyzed in Matlab (Mathworks, Natick, MA). The nonconstant portion of the image spectrum was computed by applying a 2-D fast Fourier transform. The 2-D spectrum was further radially integrated to yield a 1-D representation of the image spectrum: peaks in this representation correspond to spatial frequencies that are overrepresented in an image. The 1-D representation was then fit with Gaussian peaks to extract the periodic component with spatial frequency consistent with sarcomere length. The area under the periodic component was regarded as a metric of sarcomere content. A larger area means more sarcomeric α-actinin positive pixels are localized at a distance comparable with the sarcomere length. Cell height was calculated by measuring the height of orthogonal views of α-actinin z-stacks. Statistical differences were detected using Student’s t-test.

Western blots. Cardiac myocytes were cultured on 15-μm-wide micropatterned lines of FN with 15-μm separations on 13-kPa and 90-kPa polyacrylamide gels using the stamping protocol described above. We adapted previously published protocols to quantify soluble and polymerized tubulin (17). After rinsing samples with 4°C PBS, lysis buffer for soluble fractions (100 mM NaCl, 1 mM EDTA, 1% Triton X, 10% glycerol, 10 mM Tris, pH 7.4 in water) was added to samples for several minutes, collected, and centrifuged for 10 min at maximum speed. Supernatants were collected as soluble fractions. Samples were rinsed again in 4°C PBS and incubated with lysis buffer for polymerized fractions (soluble lysis buffer plus 1% SDS) for several minutes. Samples were scraped and buffers were collected as polymerized fractions. For both lysis buffers, Halt Protease and Phosphatase Inhibitor Cocktail (Thermo Scientific, Waltham, MA) was added immediately before lysing samples. One or two coverslips at 13-kPa and 90-kPa elastic modulus were collected for three separate primary harvests, and each harvest cycle was run on its own gel.

Protein concentrations were determined using the bicinchoninic acid (BCA) assay (Thermo Scientific). For each sample, 10–20 μg of protein (consistent for all lanes on the same gel) was mixed with 6X Laemmli sample buffer, loaded in Criterion Tris·HCl, 4–15% precast protein (consistent for all lanes on the same gel) was mixed with 6X loading buffer, and electrophoresed on SDS-PAGE. Proteins were transferred to Odyssey nitrocellulose membranes (LI-COR, Lincoln, NE). Membranes were blocked with Odyssey blocking buffer (LI-COR) for 1 h at room temperature and incubated with the following primary antibodies for 48 h at 4°C: mouse anti-α-tubulin (Sigma-Aldrich, St. Louis, MO) and goat-anti-β-actin (Santa Cruz, Dallas, TX). Membranes were rinsed and incubated with IRDye 800CW donkey anti-goat IgG (H + L) (LI-COR) for 1 h at room temperature (RT) followed by IRDye 680 goat anti-mouse IgG (H + L) (LI-COR) for 1 h at RT. Membranes were imaged with the Odyssey CLx infrared imaging system (LI-COR).

ImageJ was used to quantify band intensities. For each lane, tubulin signal (T) was normalized (norm) to β-actin signal (A) for polymerized (P) and soluble (S) fractions:

\[
T_{P,13kPa,norm} = \frac{T_{P,13kPa}}{A_{P,13kPa}},
\]

\[
T_{S,13kPa,norm} = \frac{T_{S,13kPa}}{A_{S,13kPa}},
\]

\[
T_{P,90kPa,norm} = \frac{T_{P,90kPa}}{A_{P,90kPa}},
\]

\[
T_{S,90kPa,norm} = \frac{T_{S,90kPa}}{A_{S,90kPa}}.
\]

For lanes from the same coverslip, the polymerized tubulin signal was divided by the total tubulin signal to determine the polymerized fraction:

\[
T_{13kPa,P} = \frac{T_{13kPa,P,norm}}{T_{P,13kPa,norm} + T_{S,13kPa,norm}},
\]

\[
T_{90kPa,P} = \frac{T_{90kPa,P,norm}}{T_{P,90kPa,norm} + T_{S,90kPa,norm}}.
\]

For each gel, the polymerized tubulin fraction at 90 kPa was divided by the polymerized tubulin fraction at 13 kPa to get a relative change in polymerized tubulin with matrix elasticity for each harvest:

\[
\frac{T_{13kPa,P} \text{ fraction}}{T_{90kPa,P} \text{ fraction}}.
\]

\[
\text{Polymerized tubulin fraction at 13 kPa} = \frac{T_{13kPa,P}}{T_{13kPa,P,norm}},
\]

\[
\text{Polymerized tubulin fraction at 90 kPa} = \frac{T_{90kPa,P}}{T_{13kPa,P,norm}}.
\]

Statistical differences were detected using Student’s t-test.

Traction force microscopy. Myocytes on polyacrylamide gel coverslips were transferred to normal Tyrode’s solution (1.8 mM CaCl₂, 5 mM glucose, 5 mM HEPES, 1 mM MgCl₂, 5.4 mM KCl, 135 mM NaCl, 0.33 mM Na₂HPO₄, pH 7.4) and placed on the stage of a Zeiss LSM 5 LIVE confocal microscope (Zeiss, Oberkochen, Germany) with an incubation chamber set to 35–37°C. Coverslips were scanned to find spontaneously beating, mononucleated, patterned myocytes, and several cycles were captured for each cell with a 40× Plan-Apochromat oil objective at 40 frames/s. After imaging, the coverslip was removed from the microscope, fixed, and stained using the protocol described above. Previously published techniques were used to determine displacement and traction stress vector fields from bead displacement movies using Fourier transform traction cytometry in MATLAB (Mathworks) (8, 36, 41). Statistical differences were detected using Student’s t-test.

Percent cell shortening at peak systole (€ₚ) was calculated by summing the x-magnitudes of the maximum displacement vectors (uₓ,i) on the left (l) and right (r) ends of the cell, respectively, and dividing by the diastolic length of the cell (L):

\[
\varepsilon_p = \left( \frac{\max \left[ \left( u_{x,l} \right) \right] + \max \left[ \left( u_{x,r} \right) \right]}{L} \right) = \left\{ \text{peak systolic percent cell shortening equals the maximum displacement at each end of the cell divided by diastolic cell length} \right\}.
\]

Longitudinal force vectors (fₓ,i) were calculated by multiplying the longitudinal traction stress vectors at each element i by the surface area of element i (in this case, 25 μm²). Peak systolic longitudinal force (Fₓ,p) was calculated by summing the x-magnitudes of all force vectors (fₓ,i) on the left (l) and right (r) sides of the cell and dividing by 2 to determine the average force at each end of the cell:

\[
F_{x,p} = \frac{1}{2} \left( \left[ \sum f_{x,l} \right] \left. + \left[ \sum f_{x,r} \right] \right) = \{ \text{peak systolic longitudinal force equals the average sum of all force vectors at the ends of the cell} \}.
\]

Peak systolic stress (σₓ) was calculated as

\[
\sigma_x = F_{x,p} / (bH) = \{ \text{peak systolic stress equals peak systolic longitudinal stress divided by cross-sectional area} \}
\]

where b is the average width and H is the average height of the cell for a given aspect ratio.

Peak systolic work (wₓ) was calculated as

\[
w_x = \frac{1}{2} \sum (u_{x,l} f_{x,l} + u_{x,r} f_{x,r}) = \{ \text{peak systolic work equals half the sum of all displacement vectors multiplied by force vectors} \}.
\]

Single-myocyte mathematical model. We developed a theoretical model of a force-generating myocyte to calculate how contractile force is regulated by cell dimensions, matrix elasticity, and cell
Fig. 1. Modeling stress-strain relationships in single cardiac myocytes. A: the force-velocity relationship in muscle states that stress (σ) decreases as velocity of percent shortening (d(ε)/dt) increases (solid line). A linearized form is shown by the dotted line. B: cell shortening (d(ε)/dt) to systole (ii), it shortens 6.2% at each end to generate a longitudinal force against the matrix (Fcell). The cell and the matrix both resist cell shortening. C: cell height was measured using confocal z-stacks of actin stains and was relatively constant at 3 μm. For 13-kPa gels, n = 5 for aspect ratio (AR) −2:1, n = 6 for AR −4:1, n = 5 for AR −7:1, and n = 4 for AR −10:1. For 90-kPa gels, n = 5 for AR −2:1, n = 6 for AR −4:1, n = 5 for AR −7:1, and n = 5 for AR −11:1. Bars represent standard error of the mean (SE). D: cell surface area was also relatively constant at 1.200 μm², matching the size of the micropatterned fibronectin islands. For 13-kPa gels, n = 7 for AR −2:1, n = 9 for AR −4:1, n = 7 for AR −7:1, and n = 6 for AR −10:1. For 90-kPa gels, n = 8 for AR −2:1, n = 11 for AR −4:1, n = 12 for AR −7:1, and n = 7 for AR −11:1. Bars represent SE.

elasticity. The purpose of our model is to gain independent control over matrix elasticity and cell elasticity, which are challenging to decouple experimentally, and determine which parameter has the greatest effect on contractile function. Our model solves for peak systolic percent cell shortening (ε), longitudinal force (Fcell), stress (σ), and longitudinal work (σε) based on myocyte dimensions and the elastic moduli of the matrix (Em) and the cell (Ec).

Traction force microscopy experiments of contracting rectangular myocytes have revealed that force vectors are concentrated at the two ends of the cell, where focal adhesions link the longitudinal ends of myofibrils to the extracellular matrix (36). Thus we simplified single myocytes as rectangular-shaped arrays of parallel myofibrils anchored to matrix substrates with defined elastic moduli. With this simplification, the mechanics of single cell contraction is similar to traditional measurements of cardiac trabecular muscle (20), although cell contraction in TFM is neither isometric nor isotonic because both cell shortening and stress increase with time.

Based on the assumption that single myocytes behave similarly to muscle strips (13), we applied constitutive laws for muscle contraction to relate myocyte stress generation (σ) to percent cell shortening (ε). One of the fundamental tenants of muscle physiology is the force-velocity relationship (62), which states that the force generated by a muscle increases as the velocity of shortening decreases (Fig. 1A). This phenomenon exists because more cross-bridges have time to attach if contraction velocity is slower (62). To incorporate this relationship into our model, we utilized a linearized form of the force-velocity relationship (13) based on Hill’s muscle law:

\[ F = \frac{\sigma_0}{1 - C} \left( \frac{d\epsilon}{dt} \right) \]

where contractile stress (σ) linearly increases as the rate of percent cell shortening (d(ε)/dt) decreases (Fig. 1A). The parameter constant \( \sigma_0 \) is the isometric stress, defined as \( \sigma \) when d(ε)/dt = 0, and is equivalent to the load against which myocytes do not shorten or lengthen. The parameter C, the maximum percent cell shortening, defined as d(ε)/dt when \( \sigma = 0 \). We assume uniform stress and percent shortening within the cell. Thus Eq. 13 describes how stress (σ) is regulated by the rate of percent cell shortening (d(ε)/dt), as governed by intrinsic muscle physiology.

Because both extracellular and intracellular elasticity regulate cell shortening, we next formulated a purely mechanical equation to describe force generation as a function of cell elastic modulus and matrix elastic modulus. We assumed that the amount of longitudinal force transmitted to the matrix (Fm), which is the value captured by our TFM measurements, is equal to the total longitudinal force generated by the cell (Ftotal) minus the load due to the longitudinal cell modulus (Fcell):

\[ F_{\text{cell}} = F_{\text{total}} - F_{\text{cell}} \]

To calculate Ftotal, we considered the cell as a rectangular plate (Fig. 1B). The total longitudinal force generated by a myocyte (Ftotal) is then equal to the stress (σ) multiplied by the cross-sectional area of the cell, bH, where H is the height and b is the width of the cell:

\[ F_{\text{total}} = \sigma bH \]

The load due to cell elasticity, Fcell, is calculated by multiplying the transient elastic modulus of the cell (Em) by percent cell shortening (ε) and cross-sectional area (bH):

\[ F_{\text{cell}} = E_{\text{cell}} bH \]

The relationship between traction force (Fm), substrate displacement (u), and matrix modulus (Em) can be derived as follows. Suppose a cell has a single circular focal adhesion with diameter b at each end. When the cell contracts, it applies a horizontal traction force Fm onto the elastic substrate within the area of the focal adhesion. Assuming uniform displacement u within the circular focal adhesion region and
assuming the substrate is an elastic half-space with Young’s modulus \(E_m\) and Poisson ratio \(\nu\), contact mechanics theory \((34)\) gives the relation between traction force \((F_t)\) and displacement \((u)\) as:

\[
F_t = \frac{2}{(1 + \nu)(2 - \nu)} E_m u
\]

\(= \{\text{traction force as a function of matrix modulus and displacement}\} \quad (17)

Note that this relationship is derived without ignoring any substrate deformation; it is a lumped relationship between force and displacement. In our case, displacement \((u)\) can be described via cell shortening strain \((\varepsilon)\) based on the kinematic relationship: \(\varepsilon = 2u/L\). This leads to: \(u = \varepsilon L/2\). Plugging \(u = \varepsilon L/2\) into Eq. 17 and replacing \((1 + \nu)(2 - \nu)\) with a fitting parameter \(c\), we obtain:

\[
F_t = c E_m b L/2
\]

\(= \{\text{force increases with matrix modulus and displacement at each end of the cell}\} \quad (18)

Fitting parameter \(c\) enters the equation because focal adhesions at the end are not circular and the exact size and spatial distribution varies from cell to cell. For each gel modulus, we fit \(c\) using Eq. 18 and our experimental data for peak systolic longitudinal force \((F_{L,p})\) and peak systolic percent cell shortening \((\varepsilon_p)\) (Table 1). By substituting Eqs. 15, 16, and 18 into Eq. 14 and solving for stress \((\sigma)\), we obtained a linear relationship between stress \((\sigma)\) and percent cell shortening \((\varepsilon)\):

\[
\sigma = \left(\frac{c E_m L}{2H} + E_c\right) \varepsilon
\]

\(= \{\text{stress is proportional to matrix elasticity, cell length, cell elasticity, and percent cell shortening}\}. \quad (19)

This equation illustrates how the elasticity of both the cell and the matrix contribute to stress generation.

To solve for stress \((\sigma)\) without knowledge of percent cell shortening \((\varepsilon)\), we combined Eqs. 13 and 19, which led to an ordinary differential equation for stress \((\sigma)\):

\[
\frac{d\sigma}{dt} + \frac{\gamma}{\sigma_0} \left(\frac{c E_m L}{2H} + E_c\right) (\sigma - \sigma_0) = 0
\]

\(= \{\text{differential equation for stress without percent cell shortening}\}. \quad (20)

By applying the initial condition \(\sigma(t = 0) = 0\) and integrating this differential equation from diastole \((t = 0)\) to peak systole \((t = t_p)\), we obtained peak systolic stress \((\sigma_p)\) as:

\[
\sigma_p = \sigma_0 \left(1 - e^{-\frac{\gamma}{\sigma_0} \left(\frac{c E_m L}{2H} + E_c\right) t_p}\right)
\]

\(= \{\text{peak systolic stress as a function of cell geometry, cell elasticity, matrix elasticity, and time to peak}\}. \quad (21)

In Eq. 21 and the following Eqs. 22–24, we use the aspect ratio \((s)\) and the surface area \((a)\) of the cell to represent the length \((L = \sqrt{a}s)\) and width \((b = \sqrt{a}/s)\) of the cell. We then calculated peak systolic percent shortening \((\varepsilon_p)\) using Eqs. 19 and 21 as

\[
\varepsilon_p = \frac{\sigma_0}{c E_m \sqrt{a/s} + E_c} \left(1 - e^{-\frac{\gamma}{\sigma_0} \left(\frac{c E_m L}{2H} + E_c\right) t_p}\right)
\]

\(= \{\text{percent cell shortening as a function of cell geometry, cell elasticity, matrix elasticity, and time to peak}\}. \quad (22)

Peak systolic longitudinal force \(F_{L,p}\) was derived from Eqs. 18 and 22 as

\[
F_{L,p} = \frac{c E_m a L}{2} \left(1 - e^{-\frac{\gamma}{\sigma_0} \left(\frac{c E_m L}{2H} + E_c\right) t_p}\right)
\]

\(= \{\text{peak systolic force as a function of cell geometry, cell elasticity, matrix elasticity, and time to peak}\}. \quad (23)

Note that peak systolic force \(F_{L,p}\) reaches a saturation value as matrix elasticity \(E_m\) increases, similar to previous models \((63)\). Likewise, peak systolic longitudinal work \((w_{L,p})\) was calculated from Eqs. 22 and 23 as

\[
w_{L,p} = F_{L,p} e_p \frac{L}{2} = \frac{c E_m a L}{4} \left(\frac{\sigma_0}{c E_m \sqrt{a/s} + E_c} \left(1 - e^{-\frac{\gamma}{\sigma_0} \left(\frac{c E_m L}{2H} + E_c\right) t_p}\right)\right)^2
\]

\(= \{\text{peak systolic work as a function of cell geometry, cell elasticity, matrix elasticity, and time to peak}\}. \quad (24)

For the above equations, time to peak \((t_p)\) was extracted from our experimental data for each myocyte aspect ratio on 13-kPa and 90-kPa gels (Table 1). The surface area \((a)\) and height of the cells \((H)\) were extracted from our immunostaining data and were relatively constant at 1,200 \(\mu\text{m}^2\) and 3 \(\mu\text{m}\), respectively (Fig. 1, C and D). Parameters \(\sigma_0\) and \(\gamma\) were fit using our experimental data and Eq. 24 (Table 1). Thus,

Table 1. Model parameters for single cells with indicated length-to-width aspect ratios \((s)\) on gels with 13-kPa and 90-kPa elastic modulus

<table>
<thead>
<tr>
<th>Parameter</th>
<th>13-kPa Matrix</th>
<th>90-kPa Matrix</th>
</tr>
</thead>
<tbody>
<tr>
<td>(L), (\mu\text{m})</td>
<td>51.1</td>
<td>55.0</td>
</tr>
<tr>
<td>(b), (\mu\text{m})</td>
<td>68.0</td>
<td>67.9</td>
</tr>
<tr>
<td>(H), (\mu\text{m})</td>
<td>25.7</td>
<td>26.2</td>
</tr>
<tr>
<td>(a), (\mu\text{m}^2)</td>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td>(\varepsilon_p), %</td>
<td>1200</td>
<td>1200</td>
</tr>
<tr>
<td>(F_{L,p}), (\mu\text{N})</td>
<td>0.32</td>
<td>0.35</td>
</tr>
<tr>
<td>(t_p), ms</td>
<td>68</td>
<td>89</td>
</tr>
<tr>
<td>(\sigma_p), kPa</td>
<td>4.1</td>
<td>6.3</td>
</tr>
<tr>
<td>(w_{L,p}), pJ</td>
<td>0.45</td>
<td>0.62</td>
</tr>
<tr>
<td>(n_p), kPa</td>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>(\gamma), (s^{-1})</td>
<td>0.74</td>
<td>0.74</td>
</tr>
</tbody>
</table>

\(L, b, H, a, \varepsilon_p, F_{L,p}, t_p, \sigma_p,\) and \(w_p\) were measured experimentally. \(E_c\) was chosen from the literature. \(c, \sigma_0,\) and \(\gamma\) were fit parameters. See Glossary for definition of parameters.

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given values for cell geometry, matrix elasticity, cell elasticity, and time to peak, our model predicts values for peak systolic stress, percent cell shortening, force, and work. These equations can also be used to independently modulate cell elasticity and matrix elasticity and predict the effects on contractile function.

**RESULTS**

Actin architecture is dependent on cell shape but not matrix elasticity. Concentric hypertrophy is associated with increases in myocardial stiffness (11, 37) and decreases in myocyte length-to-width aspect ratio (23, 27). We first asked if changes in microenvironmental elasticity altered the architecture of the contractile apparatus, which is essential for myocyte force generation (6, 18, 36). We took an in vitro approach by culturing neonatal rat ventricular myocytes on polyacrylamide gels with moderate (13 kPa) and high (90 kPa) elastic moduli, mimicking healthy and stiff myocardium (4), respectively. Gels were micropatterned with \( \sim 1,200 \mu m^2 \) fibronectin rectangles with aspect ratios ranging from 2:1 to 12:1 to mimic myocytes isolated from healthy and hypertrophied hearts (23).

On both moderate and stiff gels, actin alignment increased with myocyte length until reaching aspect ratio \( \sim 7:1 \), at which point it plateaued (Fig. 2, A–E), suggesting that myocyte shape is a more dominant cue for cytoskeletal alignment compared to matrix elasticity. Thus actin alignment is regulated primarily by myocyte shape, not elasticity of the microenvironment.

Sarcomere content is shape and stiffness dependent. Because sarcomeres are the force-generating elements in cardiac myocytes, we next quantified parameters related to sarcomere structure by immunostaining myocytes for sarcomeric \( \alpha \)-actinin (Fig. 3, A–D) and analyzing the 2-D Fourier spectra of the images (Fig. 3E). Sarcomere length was approximately \( \sim 1.8 \mu m \) in all cells (Fig. 3F), suggesting that sarcomere length is not dependent on cell shape or matrix elasticity, consistent with other reports (39). We also quantified sarcomere content, which is a metric of how many pixels of the \( \alpha \)-actinin immunosignal appear in organized sarcomeres, defined as periodic elements with \( \sim 2 \mu m \) spacing. On moderate gels, sarcomere content was not dependent on myocyte shape (Fig. 3G), likely because myocytes have similar surface areas and thus the amount of sarcomeres in each image was relatively constant. On stiff gels, sarcomere content was higher at aspect ratio \( \sim 2:1 \) compared with \( \sim 4:1 \) and \( \sim 7:1 \), suggesting that \( \sim 2:1 \) myocytes contain more sarcomeres despite having conserved surface area (Fig. 3G). At aspect ratios \( \sim 2:1 \) and \( \sim 7:1 \), sarcomere content was higher on stiff gels compared with moderate gels (Fig. 3G), suggesting that the amount of sarcomeres in a shape-controlled myocyte increases with the elastic modulus of the matrix. Thus sarcomere length is unaffected by myocyte shape or matrix elasticity, but at certain aspect ratios, sarcomere content is higher on stiffer matrices.

Microtubule polymerization is dependent on matrix elasticity. Microtubules are hyperpolymerized in concentric hypertrophy (53–55), which may impede myocyte shortening by increasing cell stiffness and resisting compression (58, 59). Because myocytes are mechanosensitive and remodel their cytoskeleton to adapt to their microenvironment (42), we asked if elasticity of the microenvironment directly induces microtubule remodeling. Qualitatively, single myocytes on stiff substrates had denser microtubule networks compared with those on moderate substrates, as revealed by \( \alpha \)-tubulin immunostains (Fig. 4A). To quantify microtubule polymerization, we used Western blotting to quantify the total \( \alpha \)-tubulin and the ratio of polymerized to total \( \alpha \)-tubulin in 15-\( \mu m \)-wide strands of myocytes cultured on moderate and stiff gels (Fig. 4B). Although the total tubulin content was not statistically different, the ratio of polymerized to total tubulin was approximately 27% higher on stiff gels relative to moderate gels. Thus microtubule polymerization increases with the elastic modulus of the extracellular matrix, which potentially increases the elastic modulus of the cell.

The optimal myocyte shape for contractility is regulated by the elasticity of the microenvironment. Myocyte aspect ratio decreases during the compensatory stages of concentric hyper-
trophy (23, 24), suggesting that cell shape remodeling might be an adaptive response to the microenvironment becoming stiffer. To test how myocyte shape and matrix elasticity co-regulate contractile function, we used traction force microscopy (TFM) to quantify the contractility of spontaneously contracting, shape-controlled myocytes on gels with moderate (13 kPa) and high (90 kPa) elastic moduli doped with fluorescent beads. Single myocytes attached to gels primarily at their longitudinal ends, where integrins couple myofibrils to the extracellular matrix via focal adhesion complexes (26, 36). Gel and bead displacement was concentrated at the longitudinal ends of the cell when myocytes contracted spontaneously (Fig. 5 A). We tracked bead displacement over the course of several contractile cycles for myocytes of different shapes on moderate and stiff gels and used bead displacement movies to calculate displacement and traction stress vectors (8, 41). As shown by representative peak systolic displacement vector ($\vec{u}_s$) and traction stress vector ($\vec{\sigma}_t$) maps, peak systolic displacement was highest on moderate gels (Fig. 5, B and C), but peak systolic stress was highest on stiff gels (Fig. 5, D and E) due to differences in the elastic modulus of the substrate. Thus cell shortening decreases and force generation increases when the elastic modulus of the microenvironment increases.

For the heart to function, myocytes must both shorten to reduce chamber volume and generate enough contractile force to pump blood into the vasculature. Thus percent cell shortening, longitudinal force, stress, and work are all important parameters for evaluating cardiac function (Fig. 6 A). Average percent cell shortening ($\epsilon_p$) from diastole to peak systole was relatively constant on moderate gels, but decreased with increasing aspect ratio on stiff gels (Fig. 6 B). Thus, on gels with physiological elasticity, absolute shortening was higher in longer myocytes as more sarcomeres were added in series, such that the proportion of cell shortening to diastolic cell length was relatively constant. This proportionality between myocyte length and cell shortening has also been observed in isolated rat myocytes (19), indicating that it is normal physiological behavior. However, on stiffer gels, myocyte percent cell shortening instead decreased with myocyte length (Fig. 6 B). This suggests that the high elastic modulus of the matrix...
served. tric hypertrophy, where lower aspect ratios are typically ob-
which could contribute to reductions in wall stress in concen-
creased cross-sectional area, of these cells. Thus myocytes
aspect ratios can be attributed to increased cell width, and thus
increased transmural stress. To determine how peak systolic cell stress (
force generation, we plotted representative longitudinal force
increases in myocyte length are lost when the elastic modulus
prevented longer myocytes from shortening to their full poten-
tial. Thus the gains in cell shortening that typically accompany
increases in myocyte length are lost when the elastic modulus
of the microenvironment is high.

To determine how cell shape and matrix elasticity coregulate
force generation, we plotted representative longitudinal force
(Fx) traces (Fig. 6, C and D) and average peak systolic longitudinal force (Fx,p) (Fig. 6E) for myocytes on moderate
and stiff gels. On gels with physiological elasticity, myocytes with
~7:1 aspect ratios generated the most longitudinal force at peak systole (Fig. 6, C and E). However, on stiff gels, myocytes with ~2:1 aspect ratios generated the most peak systolic longitudinal force (Fig. 6, D and E). Interestingly, the time to peak systole (tp) followed the same trends as peak systolic longitudinal force, where ~7:1 myocytes had the longest time to peak on moderate gels, consistent with previous studies (36), but ~2:1 myocytes had the longest time to peak on stiff gels (Fig. 6F). Thus peak systolic force and the time to peak contraction were highest at aspect ratio ~7:1 on gels mimicking healthy myocardium and ~2:1 on gels mimicking stiff myocardium.

Cell shape remodeling during hypertrophic remodeling is also thought to be a mechanism to reduce wall stress (27, 47).
To determine how peak systolic cell stress (σp) is regulated by
myocyte shape and matrix elasticity, we divided peak systolic longitudinal stress by the average cross-sectional cell area of each aspect ratio. We found that peak systolic longitudinal stress did decrease as myocyte aspect ratio decreased, such that smaller aspect ratios generated the lowest amount of stress, although this result was only statistically significant on 13-kPa gels (Fig. 6G). The decreased peak systolic stress at lower aspect ratios can be attributed to increased cell width, and thus increased cross-sectional area, of these cells. Thus myocytes with lower aspect ratios also have lower peak systolic stress, which could contribute to reductions in wall stress in concentric hypertrophy, where lower aspect ratios are typically observed.

Work (wp) is arguably the parameter most relevant to cardiac
output because it is a function of both cell shortening and force
generation. We found that peak systolic work (wp) was com-
parable in magnitude between moderate and stiff gels (Fig. 6H), indicating that, although myocytes on stiff gels generated
more force, they did not generate more work. Similar to our results for peak systolic longitudinal force, peak systolic work was maximized for myocytes with aspect ratio ~7:1 on moderate
gels and aspect ratio ~2:1 on stiff gels (Fig. 6H). Thus
our experimental data suggest that aspect ratio ~7:1 is functionally advantageous in normal microenvironments and aspect ratio ~2:1 is functionally advantageous in stiff microenvironments.

Extracellular elasticity regulates contractility more than intracellular elasticity. Clinical and in vivo data have shown that concentric hypertrophy is associated with both fibrosis
(21, 61) and microtubule hyperpolymerization (53–55), which could each impede myocyte shortening by increasing
the modulus of the extracellular or intracellular environ-
ment, respectively. Thus the extracellular matrix or cyto-
skeletal elements, such as microtubules, could serve as
potential therapeutic targets by reducing the load on myo-
cytes. We asked if extracellular or intracellular elasticity has
the greatest effect on contractile function. Because it is
challenging to decouple intracellular and extracellular elasticity experimentally, we instead developed an analytical
model to test the effects of elasticity and used our experi-
mental results to fit unknown parameters. As described in
methods, we formulated equations for peak systolic stress
(σp), percent cell shortening (εp), longitudinal force (Fx,p), and longitudinal work (wp) as functions of cell elastic
modulus (Ec), matrix elastic modulus (Em), cell aspect ratio
(s), and time to peak (tp):

$$
\sigma_p = \sigma_0 \left(1 - e^{\frac{-c Em V_{at}}{2H} + E_t} \right),
$$

(21)
The results of the model overlaid on experimental data are shown in Fig. 6, B, E, G, and H. Similar to our experimental results, our model showed that peak systolic percent cell shortening ($\epsilon_p$) decreased with increasing aspect ratio on stiff gels (Fig. 6B). Our model also showed that aspect ratio $\sim 7:1$ is advantageous for force and work generation on moderate gels and aspect ratio $\sim 2:1$ is advantageous on stiff gels (Fig. 6, E and H) and that peak systolic stress decreases with decreasing aspect ratio (Fig. 6G). Thus, consistent with our experimental results, our model indicates that matrix elasticity regulates the optimal shape for work generation, with lower aspect ratios maximizing work output in stiff microenvironments.

To determine if intracellular or extracellular elasticity dominates the magnitude of contractile work, we used our model to independently modulate cell elastic modulus ($E_c$) and matrix elastic modulus ($E_m$). We first held matrix elastic modulus constant at $50$ kPa and modulated cell elastic modulus, which has been reported to range between $10$ and $200$ kPa in isolated myocytes (30, 40). We chose a cell elastic modulus range of $1$–$100$ kPa and plotted peak systolic work for aspect ratios $2:1$ and $7:1$. Peak systolic work was relatively constant across the range of cell elastic moduli, with only a $\sim 20$–$25\%$ decrease in peak systolic work as cell elastic modulus increased from $1$ kPa to $100$ kPa for both aspect ratios (Fig. 7A). We next held cell elastic modulus constant at $10$ kPa and plotted peak systolic work while modulating matrix elastic modulus from $1$ to $100$ kPa. Our model also showed that aspect ratio $\sim 7:1$ is advantageous for force and work generation on moderate gels and aspect ratio $\sim 2:1$ is advantageous on stiff gels (Fig. 6, E and H) and that peak systolic stress decreases with decreasing aspect ratio (Fig. 6G). Thus, consistent with our experimental results, our model indicates that matrix elasticity regulates the optimal shape for work generation, with lower aspect ratios maximizing work output in stiff microenvironments.
For 7:1 myocytes, peak systolic work was maximized at a matrix elastic modulus of $20 \text{kPa}$ and dropped $60\%$ when matrix elastic modulus increased to $100 \text{kPa}$ (Fig. 7B), which is a marked difference compared with modulating cell elastic modulus. Myocytes at 2:1 were less sensitive to increases in matrix elastic modulus, as peak systolic work was maximized when matrix elastic modulus was $50 \text{kPa}$ and only dropped $25\%$ when matrix elastic modulus increased to $100 \text{kPa}$ (Fig. 7B). This suggests that lower aspect ratios can better adapt to increases in matrix elastic modulus because peak systolic work was mostly constant when matrix elastic modulus was high. The comparison of the two aspect ratios also illustrates that 7:1 generates more work when the elastic modulus of the matrix is below $40 \text{kPa}$ and 2:1 generates more work when the elastic modulus of the matrix is above $40 \text{kPa}$, indicating that lower aspect ratios are more favorable when the microenvironment becomes stiffer due to conditions such as fibrosis. Thus our model predicts...
that matrix elasticity dominates over cell elasticity and that lower aspect ratios generate more work compared with moderate aspect ratios when the elastic modulus of the matrix increases due to conditions such as fibrosis.

DISCUSSION

Concentric hypertrophy is associated with diverse intracellular and extracellular remodeling, which are coupled and thus difficult to understand as independent mechanisms of pathogenesis. With this study, we asked if lower myocyte aspect ratios, such as those observed in concentric hypertrophy, maximize contractility when the extracellular matrix becomes stiffer due to factors such as fibrosis. We used an in vitro system to replicate the shapes of myocytes from healthy and hypertrophied hearts and quantified their contractile function on gels with normal and high elastic moduli. Peak systolic work was maximized at \( \sim 7:1 \) aspect ratios on gels mimicking healthy myocardium (13 kPa) and \( \sim 2:1 \) aspect ratios on gels with elastic moduli in the range of fibrosis (90 kPa). Microtubule polymerization was higher on stiff gels, suggestive of a decrease in intracellular elasticity. To delineate the contributions of intracellular versus extracellular elasticity to contractile dysfunction, we developed a mathematical model, which revealed that matrix elasticity has a stronger influence on contractility compared with cell elasticity. Together, our results suggest that myocyte shape is potentially tuned to maximize contractility based on the mechanical properties of the extracellular matrix, which has implications for understanding why cardiac myocyte shape remodels in diseases such as hypertrophy.

Our analysis of actin and sarcomere structure revealed that several structural parameters are regulated by myocyte shape and matrix elasticity. Sarcomere length was constant across all myocyte aspect ratios and matrix elasticities, consistent with previous in vivo and in vitro reports (39). Previous studies have shown that actin alignment in mesenchymal stem cells is regulated by both cell shape and matrix elasticity (63). We similarly observed increases in actin alignment with cell shape, but found no dependency of actin alignment on matrix elasticity. We also found that sarcomere content (a measure of the amount of periodic \( \alpha \)-actinin structures) was highest in myocytes with aspect ratio \( \sim 2:1 \) on stiff gels compared with other aspect ratios on stiff gels and the same aspect ratio on moderate gels. This suggests that sarcomerogenesis tends to be more pronounced on stiff gels, which conflicts slightly with previous reports suggesting that sarcomere structures are optimized on gels with physiological elasticity (15, 34, 39). However, these discrepancies could exist because we strictly defined myocyte shape by using micropatterned substrates. On unpatterned substrates, the cells can assume a broader range of cytoskeletal architectures and thus might have increased sensitivity to matrix elasticity. Previous studies have also reported highly aligned sarcomere structures in cardiac myocytes cultured on micropatterned fibronectin islands on polydimethylsiloxane (6, 22), which has an elastic modulus in the range of 1 MPa, indicating that well-developed sarcomeres form on substrates even stiffer than those evaluated in this study. The increased sarcomere content we observed in \( 2:1 \) myocytes on stiff gels could potentially contribute to the increased contractile work produced by these cells, in addition to the effects of cell geometry as described in our model and discussed in detail below.

Concentric hypertrophy can be induced by a variety of pathologies that induce pressure overload, such as aortic valve stenosis or hypertension. In response, the ventricular wall becomes fibrotic and thickens to offset the increased load (27, 37). Myocytes also become wider (23, 24), but the functional consequences of myocyte shape changes have not been clearly identified. By taking an in vitro approach, we independently modulated matrix elasticity and myocyte shape to determine how these two parameters coregulate myocyte contractile function. Percent cell shortening at peak systole was relatively constant on moderate gels, which is expected because absolute cell shortening typically increases as myocytes grow longer and more sarcomeres are added in series (19). However, this same trend was not observed on stiff gels, where percent cell shortening instead decreased with aspect ratio, likely because the matrix offered excessive resistance against cell shortening. Thus myocytes in stiff microenvironments do not benefit functionally from increases in myocyte length. As a consequence, \( \sim 7:1 \) myocytes generated the most work on moderate gels and \( \sim 2:1 \) myocytes generated the most work on stiff gels, which were the shortest of all tested shapes. Thus, in stiff microenvironments, cell width appears to be more beneficial than cell length, which is consistent with how myocyte shape changes in concentric hypertrophy (23, 24). Our data also showed that lower aspect ratios generate less peak systolic stress, suggesting that lower aspect ratios could also reduce wall stress, a
widely proposed explanation for cell shape remodeling in concentric hypertrophy (27, 47). Our data are suggestive of a model describing myocyte shape remodeling in concentric hypertrophy as a compensatory response to increased matrix elastic modulus, where myocyte shape adapts to maximize contractility in response to extracellular matrix remodeling (Fig. 8).

To understand why an optimal cell aspect ratio exists and depends on matrix elasticity, we can rewrite Eq. 24 from our model in the following form:

\[
\frac{w_{x,p}}{cE_m aL} = \frac{\sigma_0}{4}\left(\frac{cE_m \sqrt{a s}}{2H} + E_c\right)^2 \left[1 - \frac{\gamma}{\sigma_0} \left(\frac{cE_m \sqrt{a s}}{2H} + E_c\right)t_p\right]^{2}.
\]

(Mathematically, it can be seen from the above equation that peak systolic work \(w_{x,p}\) decreases with aspect ratio \(s\) if we keep the multiplying factor in the second bracket constant, while it increases with aspect ratio \(s\) if the multiplying factor in the first bracket is kept constant. Thus the product of these two brackets yields a nonmonotonical relationship between peak systolic work \(w_{x,p}\) and cell aspect ratio \(s\), with an optimal aspect ratio at which peak systolic work \(w_{x,p}\) is maximized. Other parameters also dictate the optimal aspect ratio, such that it is a function of matrix elastic modulus \(E_m\), cell elastic modulus \(E_c\), time to peak contraction \(t_p\), and fit parameters for isometric stress \(\sigma_0\) and maximum percent cell shortening rate \(\gamma\). Using parameter values either measured experimentally, fit with our experimental data, or taken from the literature, we found the optimal aspect ratio to be \(\sim 7:1\) on 13-kPa matrix and \(\sim 2:1\) on 90-kPa matrix, similar to our experimental data. The nonmonotonical relationship between peak systolic work \(w_{x,p}\) and cell aspect ratio \(s\) can also be understood as a balance between cell length and cell width. When a rectangular cell gets longer (and aspect ratio \(s\) gets larger), the magnitude of absolute shortening by each individual myofibril increases. However, the cell also gets thinner when aspect ratio \(s\) increases, which decreases the total number of myofibrils in the cell. Thus the cell as a whole pulls on a smaller area of matrix, which decreases the total amount of work done on the matrix. The competition of these two factors leads to the existence of an optimal aspect ratio.

Fig. 8. Matrix elasticity determines the optimal myocyte shape for contractile function. Our proposed model for myocyte shape remodeling in concentric hypertrophy. In a healthy heart, myocytes have an aspect ratio of \(\sim 7:1\). In pressure overload, matrix elastic modulus increases, microtubules hyperpolymerize, and cell shortening decreases. To compensate, myocyte aspect ratio decreases to maximize cell shortening and force generation in response to increased matrix elastic modulus. On the scale of the ventricle, this cellular remodeling could contribute to the development of ventricular wall thickening concentric hypertrophy. RV, right ventricle; LV, left ventricle.
Besides the mechanical mechanisms described above, we also found that time to peak systole contributes to an optimal aspect ratio. As indicated by Eq. 24, peak systolic work \( w_{s,p} \) monotonically increases with time to peak contraction \( t_p \). Thus larger \( t_p \) leads to larger peak systolic work \( w_{s,p} \). Interestingly, time to peak contraction followed the same trends we observed for peak systolic force, where aspect ratio \( \sim 7:1 \) had the longest time to peak on moderate gels and \( \sim 2:1 \) had the longest time to peak on stiff gels. Correlations between time to peak and twitch amplitude have been observed previously in isolated rat myocytes (19), providing ex vivo evidence that contraction dynamics regulate the magnitude of contractile stress. Time to peak contraction is primarily regulated by calcium, suggesting that remodeling of calcium handling proteins, which is observed in both pressure-overload hypertrophy and heart failure (60), could have a significant impact on contraction strength by altering contraction dynamics. Previous in vitro studies have shown that myocyte shape (36) and substrate stiffness (34, 44) can each independently regulate calcium handling, but further studies are needed to understand how shape- and elasticity-dependent differences in contractility are governed by calcium.

Microtubules in hypertrophied myocytes are hyperpolymerized compared with healthy myocytes (53–55), which is thought to impede cell shortening (5, 31) because microtubules resist compression (50). Our results showed that increased matrix elastic modulus induces microtubule hyperpolymerization, which could contribute to the reduced percent cell shortening we observed on stiff gels. Thus one potential mechanism that could be drawn from our data is that stiff matrix induces microtubule hyperpolymerization, which increases cell elastic modulus, resists cell shortening, and underlies contractile dysfunction. Because it is experimentally difficult to uncouple matrix elasticity and cell elasticity, we used our analytical model to independently modulate these two parameters. Our model predicted that variations in matrix elasticity contribute more to peak systolic work compared with cell elasticity, suggesting that targeting microtubules is less likely to be an effective treatment in concentric hypertrophy. Interestingly, studies in pressure-overloaded rats (51) and felines (3) have shown that microtubules are hyperpolymerized in hypertrophied hearts, but treatment with the depolymerizing agent colchicine did not restore contractile function. These studies are consistent with the conclusion from our analytical model that microtubules and associated increases in intracellular elastic modulus are not the primary regulator of contractile dysfunction in concentric hypertrophy.

As with many in vitro studies, the implications of our work are limited by differences between in vivo and in vitro environments and therefore must be interpreted with caution. Observations made in individual cardiac myocytes cultured on elastic hydrogels might not translate to cardiac myocytes in the heart, which are coupled to other myocytes and are surrounded by an extracellular matrix consisting of collagen fibers. Another limitation of our work is that we did not make experimental measurements of cell elastic modulus for our model. Instead, we used a single value from the literature. We also used the same value of cell elastic modulus for both moderate and stiff gels, which may or may not be accurate, as suggested by our microtubule data. Another limitation of our model is that it is only applicable to 2-D rectangular muscle cells with all sarcomeres aligned along the same direction, which we assume could be extended to elongated, cylindrical 3-D cells. Our model is also based on the assumption that single myocytes are governed by the same stress-strain relationships as whole muscle (13). However, the match between our experimental and theoretical data suggests that the physiology of whole muscle, which is on the centimeter scale, is derived from the biophysical behavior of single myocytes, which are on the micrometer scale. Thus certain cellular behaviors scale to the organ level, illustrating how diseases such as concentric hypertrophy impact multiple spatial scales and thus require a systems-level approach to decipher disease mechanisms.

Current therapies for concentric hypertrophy are typically dependent on the underlying cause. For example, in the case of aortic valve stenosis, valve replacement surgery has been shown to alleviate the mechanical overload and reverse hypertrophic growth (37). Conversely, pharmacological treatments, including ACE inhibitors, beta-blockers, and calcium-channel blockers, have had limited success in reversing the phenotype (37). Our data suggest that the extracellular matrix could serve as a potential therapeutic target in concentric hypertrophy. Using pharmacological treatments to remodel the mechanical microenvironment of diseased hearts instead of modulating ion channels or chemical signaling could hold promise for reversing the contractile dysfunction typically associated with cardiac pathologies. Thus the extracellular matrix is not a passive support structure but instead is a powerful regulator of the structural and functional phenotype of cardiac myocytes in health and disease, suggesting that it also has potential as a therapeutic target.

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Present address for M. L. McCain: Dept. of Biomedical Engineering, Viterbi School of Engineering, Univ. of Southern California, Los Angeles, CA 90089.

Present address for F. S. Pasqualini: Dept. of Anesthesia, Brigham and Women’s Hospital, Boston, MA 02115.

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DISCLOSURES

No conflicts of interest, financial or otherwise, are declared by the author(s).

AUTHOR CONTRIBUTIONS


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